

# Building an IoT-Class Device

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# Summary

- What is an IoT device?  
Why would I want to build one?
- Defining the playground:  
purpose, environment, use cases, threats.
- Identifying the constraints: time, materials, means.
- System design: HW, SW, development environment
- The gory details:
  - HW / SW selection
  - Identifying and integrating the key components
- Consideration about optional features.

# What is an IoT device? Why would I build one?

## **IoT device:**

*(semi) autonomous agent, producing and/or consuming information, mostly by interacting with other IoT agents.*

## **Not a new concept:**

home, industry automation have existed for a long time.

**What is new:** plummeting costs, pervasive connectivity.

**An unprecedented opportunity for data collection  
and automation.**

# IoT devices are not born equal

## Topology - Nodes vs. Leaves:

- Multi-purpose vs. single task
- Beefier vs. leaner specs
- Some Linux flavor vs. RTOS or minimalistic Linux

## Security threats:

- Direct exposure to the Internet vs. tamer intranet
- Open services running
- Risk of physical tampering

# Goals and Constraints

## Goals

- **Rapid development**
- **Avoid investing time in distro technology that is not close to the use-case.**

## Constraints

- **Certain use-cases are not yet standardized.**
- **Supporting them means choosing among competing options.**

# The unit we want to build

- **High-End Leaf**

has functionality of its own, others can contact it

- **No extreme cost optimization**

Wherever possible, relies on stock components

- **Ease of maintenance**

Keeping it up-to-date is simple and it is not labour-intensive

- **Self-contained**

Supports development for its own applications

# Choosing HW and Distro

- **Prefer a familiar Distro, even if suboptimal:**  
it will pay off when debugging or looking for help.
- **Prefer boards supported by the Distro directly:**  
A HW vendor will eventually stop upgrading custom images.
- **Prefer HW fully supported by mainline kernel:**  
it has a larger user base than the single Distro you have chosen.
- **Adjust security measures to the worst case scenario, in case of a breach. Data sensitivity?**



# Why this approach?

## Minimize the Total Cost of Ownership

The TCO includes:

- Bill of Materials
- Training on new tools (unless you really want to)
- Development time (see previous point)
- Maintenance of custom code (it will bitrot)
- Tracking of upstream bugs, especially security

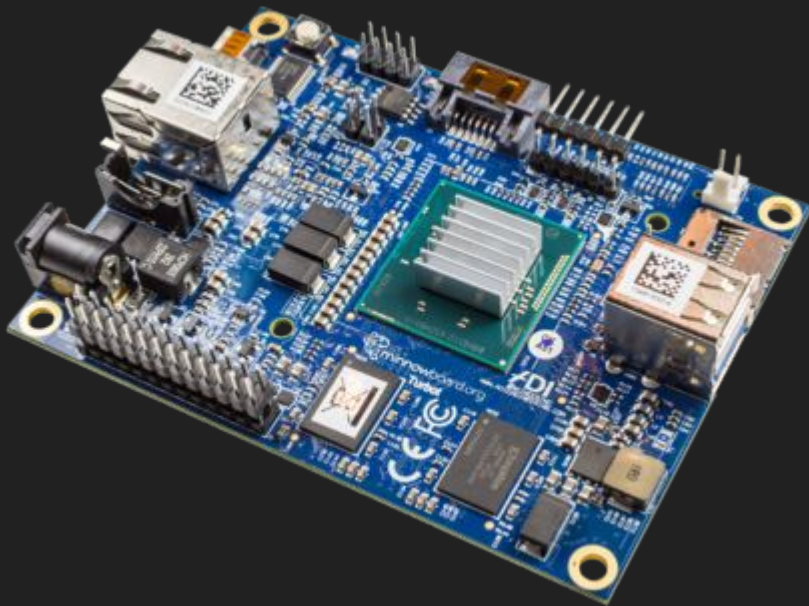
***A PC-like device can exploit a wealth of resources, unavailable on any alternative solution.***

# When does this make sense?

- Small team, limited bandwidth - **focus on the use case.**
- Time constrained development. **Reuse, do not reinvent.**
- Little expertise in certain areas (ex: distro maintenance)
- HW cost not critical (**small batch / high profitability**).
- **Need to be future proof.**
- User not a threat to security (DRM-free, no local threats).
- Desire to tap into large base of developers familiar with mainstream distros, rather than requiring specific training.
- Don't want to do unnecessary rebuilds of unrelated components.

# Practical Example

## MinnowBoard Turbot [1]



- PC-like UEFI BIOS
- Small form factor
- Passive cooling
- Low power
- Boots regular distros (Debian, Ubuntu, RH)
- USB3:  
easy to expand

Alternatives: RaspBerry PI 2 & 3

# Distro selection

Distro chosen: Debian

But it could have been anything sufficiently familiar:  
Ubuntu/Snappy, OpenSuse, RedHat, etc.

Do not spend time re-learning how to get the base distro up and running unless it brings major gains.

# Distro configuration - 1

- Dump the standard installer image onto an USB stick
- Proceed with the installation on an SD card (MinnowBoard doesn't have internal storage), following the typical installation procedure for the chosen distro.
- Use the most minimalistic configuration available: those components that are specifically needed for the required use case will be installed in a 2nd phase

# Distro configuration - 2

- Install, configure and enable ssh services.  
Follow best practices to ensure that the service is installed both properly and securely. Ex: [2].
- Configure and enable the firewall.  
Allow only what is needed. Block the rest.  
Even use a script generator is better than skipping this step. Ex: [3]

**Make a copy of the SD card: it will be useful as base for either creating other projects, or as restore point.**

# Designing the Application

Make the service available through ad-hoc interface.

**Anything that fulfills the need will do:**

data stream, archive with records, http page, ...

Profile and perform optimizations only in the face of a problem that can be clearly identified and measured.

# Sensors/Actuators integration

## Embedded vs Discrete

- Many choices of bus: I2C / SPI / Camera / ...
- High bandwidth, when needed.
- Minimal space occupation.
- Same electrical circuit as the SoC.
- Comparatively low power - good for battery life.
- Special debugging rig.
- Direct electrical interface
- One bus type: USB
- USB3 can have high throughput.
- Can take up significant space.
- USB hub can provide electrical decoupling.
- High power scenario, typical with USB hub.
- Debug on a normal PC.
- USB hub as protection.



# Practical Example - continued

**Create an IP Camera**

**for monitoring purposes.**

**Choosing the sensor:**

- simple USB camera available through v4l2.

**Streaming Solution:**

- Gstreamer server through secure connection.

# Practical Example - configure

- Install gstreamer-tools on the sd card.
- Set Up a gstreamer source using the selected USB camera sensor [10].
- Establish a permanent ssh connection between the IP camera and its consumer [6].

Not efficient, but easy to setup and verify.

## Avoid growing the attack surface.

- On the consumer side, establish the gstreamer sink that will use the data produced on the camera [11].

# Practical Example - Pain Points

- Not fully standardized.
- Multiple Competing Solutions.
- Risk to invest resources into a losing solution.

Is there a real need that justifies the feature(s)?

- Advanced Software updater
- Extra security features
- Interoperability APIs

# Practical Example - SW Updater

- Distro package manager:
  - Very well tested
  - Can cause conflicts, with partially completed updates
- Image based approach:
  - Reliable
  - Bandwidth Intensive
- Advanced updaters:
  - Container-based: ostree/flatpack [7] - snappy[8]
  - Diff-based: ClearLinux [9]
  - Very optimized
  - Fairly new, with limited use-base

# Practical Example - Extra Security

Examples: IMA, SMACK, SELinux, Apparmor

**IFF used correctly, they can greatly harden the device**

Is there enough competence to use them proficiently?

**Most likely they will (greatly) hinder the development.**

Does the worst case scenario justify their use?

# Practical Example - Interoperability

## Various options:

- OCF [4],
- Node-RED [10]
- Soletta [11]

The cost: creating and maintaining bindings

**What is the additional value?**

**Be opportunistic**

**Questions?**



**Thank you!**

# Backup Info

# References

- [1]. [http://wiki.minnowboard.org/MinnowBoard\\_Turbot](http://wiki.minnowboard.org/MinnowBoard_Turbot)
- [2]. <http://www.cyberciti.biz/tips/linux-unix-bsd-openssh-server-best-practices.html>
- [3]. [http://iptables.xn--rzeniczak-sbc.pl/generator\\_setup.php](http://iptables.xn--rzeniczak-sbc.pl/generator_setup.php)
- [4]. <https://openconnectivity.org/>
- [5]. <http://www.einarsundgren.se/gstreamer-basic-real-time-streaming-tutorial/>
- [6]. <https://www.everythingcli.org/ssh-tunnelling-for-fun-and-profit-autossh/>
- [7]. <https://ostree.readthedocs.io/en/latest/> - <http://flatpak.org/#page-top>
- [8]. <https://developer.ubuntu.com/en/snappy/>
- [9]. <https://clearlinux.org/features/software-update>
- [10]. <http://nodered.org/>
- [11]. <https://solettaproject.org/>

# Example - commands

[10]. **Starting the gstreamer capture pipeline:**

```
gst-launch-1.0 v4l2src device="/dev/video0" ! videoconvert !  
videotoolbox ! video/x-raw,width=800,height=600 ! avenc_mpeg4 !  
rtppay config-interval=3 ! udpsink host=127.0.0.1 port=5200
```

[11]. **Showing the gstreamer video feed:**

```
gst-launch-1.0 -v udpsrc port=5200 caps = "application/x-rtp,\  
media=\(string\)video,\ clock-rate=\(int\)90000,\  
encoding-name=\(string\)MP4V-ES,\ profile-level-id=\(string\)1,\  
config=\(string\)000001b001000001b58913000001000000012000c48d8800cd  
3204709443000001b24c61766335362e312e30,\ payload=\(int\)96,\  
ssrc=\(uint\)2873740600,\ timestamp-offset=\(uint\)391825150,\  
seqnum-offset=\(uint\)2980" ! rtppay ! avdec_mpeg4 !  
autovideosink
```